# AX20 Robot Controller



Our latest high-performance, multi-tasking controller features hardware and software enhancements resulting in shorter cycle times. Programming is fast and flexible with additional options available through the teach pendant. With the internal manual/diagnostic function, maintenance can be done from a remote location. The AX20 also complies to international standard safety circuits for security you can count on.

### **Control Features**

- > 50mm short pitch move 30% faster
- > International standard safety circuit
- > High-speed interference detection
- Fully digital drive with high-speed DSP motion control
- > Simplified maintenance

## **Enhanced Software**

- Real Time Operating System (RTOS) plus embedded WindowsNT®
- > Improved robot motion
- > Easy tools to develop and validate robot programs
- Software PLC directly controls peripherals
- > Offline programming
- > Visual maintenance with online manual

### **Teach Mode**

- > Easy to operate ergonomic design
- > Enhanced color graphic Windows® display
- > Pendant display functions can be customized
- > Optional digital touch screen

# **Applications**

Used on all Nachi robot products

### **Open Concept**

- > Extends to industry standard bus (ISA/PCI)
- Supports WindowsNT® applications (with extra printed circuit board)



# **AX20 Robot Controller**



Controlled Axis		
Controlled Axis		Simultaneous 7 axes (maximum 9 axes optional)
		Total 18 axes (extended control cabinet)
Servo Motor / Positioning Device	e	AC servo motor / Absolute Encoder
Programming Language(s)		Teaching playback (Standard Step / Function Record method)
		JIS SLIM language (optional)
Program Number / Memory Cap	acity	IEC1131 software PLC (Nachi Soft-PLC)  9,999 programs / 16MB (160,000 steps equivalent)
Robot Cables (Wire Harness)	dacity	Standard cable length 5m (for floor mounted or shelf-mounted type)
from Controller to Manipulator		(10m, 15m 20m and 25m cables are optional)
Internal / External Memory		Flash memory / Compact Flash card Interface
User Interface		Interface PB panel on front of controller, additional mounting inside of door & side panel
Construction / IP Rating		Enclosed box with IP54 Rating
Cooling System		Direct cooling system
Input Supply Voltage(s)		Without transformer: AC200V - 220V ± 10% (3 phase, 50/60Hz)
		With transformer: AC380V ~ 480V ± 10% (3 phase, 50/60Hz)
Ambient Temperature / Humidity		0-45°C / 20-85% (No Condensation)
Power Consumption  Controller Cabinet Dimensions		Peak power while in playback of operation program: ST Series: Approx. 5kVA SG Series: Approx. 5kVA SC35/50 Series: Approx. 3kV/
		SC15: Approx. 2kVA SC Heavy Payload Series: Approx. 5kVA
		Lift500 series approx. 9kVA (3 axes specification)  W450 x H782 x D550mm (without controller casters); Height: 882 (with controller casters)
Controller Capiller Difficusions		W450 x H762 x D550mm (without controller casters); Height: 1295 (with controller casters)  W450 x H1195 x D550mm (without controller casters); Height: 1295 (with controller casters)
Weight Coated Color		Approx. 85kg without transformer
		Approx. 165kg with transformer
		Munsell 10GY9/1
Operator Protective Function		Teach model/Playback mode interlock
		Deadman switch
		Emergency stop button (Operation panel / Teach pendant / External signal input)
		Guard fence door interlock signal (SFP – Safety Plug)
		Enable switch interface
Self-Diagnosis Function		Used to self-diagnose errors of the robot and controller (available for approx. 700 types of errors)
Error Detection Function		Used to monitor the status of the robot and controller at all times
		Used to make the robot an immediate stop when an error occurs
Teach Pendant	Screen	6.5-inch color TFT LCD (256-color display of 640 x 480 with a back light)
	TP Weight	Approx. weight 1.3 kg (excluding connection cables)
	Cable Length	Standard TP cable length 8m (15m, 20m, 25m and 30m cables are optional)
	Deadman Switch	Single-hand three-position Deadman switch is standard (optional two handed)
	Touch Screen	Digital Touch Screen (Optional)
	Language Support	
		Japanese are optional): Japanese, English, German, Korean, Taiwanese (traditional Chinese), Portuguese, Spanish,
		French, Chinese (simplified Chinese), Italian, and Dutch)
Option Functions		,,,,,,,,,,,,,,
Primary Power Voltage		For out-of-the-standard primary power voltage (AC200-220V)
Primary Power Voltage Compact Flash Card Interface		For out-of-the-standard primary power voltage (AC200-220V) The compact flash card slot is installed
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Primary Power Voltage Compact Flash Card Interface Servo Gun Auxiliary Axis  Slide Positioner on other Auxiliar Positioner Axis Field Bus  Input / Output  Extended DC I/O XYZ Shift Palletizing Robot Language Built-In PLC  Standard Functions Accuracy  Tool Designation Automatic Tool Length Calculate	or	For out-of-the-standard primary power voltage (AC200-220V) The compact flash card slot is installed Spot welding gun is controlled — gun specification (gun quantity, gun change) and simultaneous usage with another auxiliary axes depends on the individual application (additional amplifier may be necessary) Slide positioner is servo controlled (additional amplifier may be necessary) Positioner is servo controlled (additional amplifier may be necessary) Device Net, Profibus-DP, Interlink, RIO, CC-LINK, maximum 2 communication channels per controller. (Ex. 1 Master and 1 Slave, 2 Master or 2 Slave) Input 32 DC24V (input resistance 3k, input current 3mA or greater, sinking style input) Output 32 DC24V (Output voltage DC24V, +/- 3V at 100mA) Additional 32/32 or 64/64 for a total of 64/64 or 96/96 I/O) Recorded point is played back with XYZ parallel shift amount Palletizing & de-palletizing teaching programmed by integrated user friendly pattern definition JIS SLIM language Offline programming software tool (ICS Triplx ISaGRAF Workbench)  A selection from 8 (0-1000mm) of in-position accuracy can be designated on each step. In-position or path-through can also be designated 32 unique tools can be defined for use on taught positions.
Primary Power Voltage Compact Flash Card Interface Servo Gun Auxiliary Axis  Slide Positioner on other Auxiliar Positioner Axis Field Bus  Input / Output  Extended DC I/O XYZ Shift Palletizing Robot Language Built-In PLC  Standard Functions Accuracy  Tool Designation Automatic Tool Length Calculated	or G Calculator	For out-of-the-standard primary power voltage (AC200-220V) The compact flash card slot is installed Spot welding gun is controlled — gun specification (gun quantity, gun change) and simultaneous usage with another auxiliary axes depends on the individual application (additional amplifier may be necessary) Slide positioner is servo controlled (additional amplifier may be necessary) Positioner is servo controlled (additional amplifier may be necessary) Device Net, Profibus-DP, Interlink, RIO, CC-LINK, maximum 2 communication channels per controller. (Ex. 1 Master and 1 Slave, 2 Master or 2 Slave) Input 32 DC24V (input resistance 3k, input current 3mA or greater, sinking style input) Output 32 DC24V (Output voltage DC24V, +/- 3V at 100mA) Additional 32/32 or 64/64 for a total of 64/64 or 96/96 I/O) Recorded point is played back with XYZ parallel shift amount Palletizing & de-palletizing teaching programmed by integrated user friendly pattern definition JIS SLIM language Offline programming software tool (ICS Triplx ISaGRAF Workbench)  A selection from 8 (0-1000mm) of in-position accuracy can be designated on each step. In-position or path-through can also be designated 32 unique tools can be defined for use on taught positions. Automated tool length calculation by selecting taught program
Primary Power Voltage Compact Flash Card Interface Servo Gun Auxiliary Axis  Slide Positioner on other Auxiliar Positioner Axis Field Bus Input / Output  Extended DC I/O XYZ Shift Palletizing Robot Language Built-In PLC  Standard Functions Accuracy  Tool Designation Automatic Tool Length Calculate Automatic Tool Moment of Inerti	or G Calculator	For out-of-the-standard primary power voltage (AC200-220V) The compact flash card slot is installed Spot welding gun is controlled — gun specification (gun quantity, gun change) and simultaneous usage with another auxiliary axes depends on the individual application (additional amplifier may be necessary) Slide positioner is servo controlled (additional amplifier may be necessary) Positioner is servo controlled (additional amplifier may be necessary) Device Net, Profibus-DP, Interlink, RIO, CC-LINK, maximum 2 communication channels per controller. (Ex. 1 Master and 1 Slave, 2 Master or 2 Slave) Input 32 DC24V (input resistance 3k, input current 3mA or greater, sinking style input) Output 32 DC24V (Output voltage DC24V, +/- 3V at 100mA) Additional 32/32 or 64/64 for a total of 64/64 or 96/96 I/O) Recorded point is played back with XYZ parallel shift amount Palletizing & de-palletizing teaching programmed by integrated user friendly pattern definition JIS SLIM language Offline programming software tool (ICS Triplx ISaGRAF Workbench)  A selection from 8 (0-1000mm) of in-position accuracy can be designated on each step. In-position or path-through can also be designated 32 unique tools can be defined for use on taught positions. Automated tool length calculation by selecting taught program Automatic tool weight and COG is calculated by running designated program
Primary Power Voltage Compact Flash Card Interface Servo Gun Auxiliary Axis  Slide Positioner on other Auxiliar Positioner Axis Field Bus Input / Output  Extended DC I/O XYZ Shift Palletizing Robot Language Built-In PLC  Standard Functions Accuracy  Tool Designation Automatic Tool Length Calculate Automatic Tool Moment of Inerti	or G Calculator	For out-of-the-standard primary power voltage (AC200-220V) The compact flash card slot is installed Spot welding gun is controlled — gun specification (gun quantity, gun change) and simultaneous usage with another auxiliary axes depends on the individual application (additional amplifier may be necessary) Slide positioner is servo controlled (additional amplifier may be necessary) Positioner is servo controlled (additional amplifier may be necessary) Device Net, Profibus-DP, Interlink, RIO, CC-LINK, maximum 2 communication channels per controller. (Ex. 1 Master and 1 Slave, 2 Master or 2 Slave) Input 32 DC24V (input resistance 3k, input current 3mA or greater, sinking style input) Output 32 DC24V (Output voltage DC24V, +/- 3V at 100mA) Additional 32/32 or 64/64 for a total of 64/64 or 96/96 I/O) Recorded point is played back with XYZ parallel shift amount Palletizing & de-palletizing teaching programmed by integrated user friendly pattern definition  JIS SLIM language Offline programming software tool (ICS Triplx ISaGRAF Workbench)  A selection from 8 (0-1000mm) of in-position accuracy can be designated on each step. In-position or path-through can also be designated 32 unique tools can be defined for use on taught positions. Automated tool length calculation by selecting taught program  Automated tool weight and COG is calculated by running designated program
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Compact Flash Card Interface Servo Gun Auxiliary Axis  Slide Positioner on other Auxiliar Positioner Axis Field Bus  Input / Output  Extended DC I/O XYZ Shift Palletizing Robot Language Built-In PLC  Standard Functions Accuracy  Tool Designation Automatic Tool Length Calculate Automatic Tool Weight and COC	or G Calculator	For out-of-the-standard primary power voltage (AC200-220V) The compact flash card slot is installed Spot welding gun is controlled — gun specification (gun quantity, gun change) and simultaneous usage with another auxiliary axes depends on the individual application (additional amplifier may be necessary) Slide positioner is servo controlled (additional amplifier may be necessary) Positioner is servo controlled (additional amplifier may be necessary) Device Net, Profibus-DP, Interlink, RIO, CC-LINK, maximum 2 communication channels per controller. (Ex. 1 Master and 1 Slave, 2 Master or 2 Slave) Input 32 DC24V (input resistance 3k, input current 3mA or greater, sinking style input) Output 32 DC24V (Output voltage DC24V, +/- 3V at 100mA) Additional 32/32 or 64/64 for a total of 64/64 or 96/96 I/O) Recorded point is played back with XYZ parallel shift amount Palletizing & de-palletizing teaching programmed by integrated user friendly pattern definition JIS SLIM language Offline programming software tool (ICS Triplx ISaGRAF Workbench)  A selection from 8 (0-1000mm) of in-position accuracy can be designated on each step. In-position or path-through can also be designated 32 unique tools can be defined for use on taught positions. Automated tool length calculation by selecting taught program Automated tool length calculation by selecting taught program Automated tool moment of inertia is calculated by running designated program Continuous real-time internal self checking of the robot and controller for fault or errors conditions, (700 types of errors). The robot stops immediately when error is detected.  Maximum 2,048 logical I/O points for use with Soft-PLC  1. Screen Editor – addition, deletion and copy of every move step and function is available; recorded position can also be edited
Primary Power Voltage Compact Flash Card Interface Servo Gun Auxiliary Axis  Slide Positioner on other Auxiliar Positioner Axis Field Bus  Input / Output  Extended DC I/O XYZ Shift Palletizing Robot Language Built-In PLC  Standard Functions Accuracy  Tool Designation Automatic Tool Length Calculate Automatic Tool Moment of Inerti Self Checking Error Detection  Logical I/O	or G Calculator	For out-of-the-standard primary power voltage (AC200-220V) The compact flash card slot is installed Spot welding gun is controlled — gun specification (gun quantity, gun change) and simultaneous usage with another auxiliary axes depends on the individual application (additional amplifier may be necessary) Slide positioner is servo controlled (additional amplifier may be necessary) Positioner is servo controlled (additional amplifier may be necessary) Device Net, Profibus-DP, Interlink, RIO, CC-LINK, maximum 2 communication channels per controller. (Ex. 1 Master and 1 Slave, 2 Master or 2 Slave) Input 32 DC24V (input resistance 3k, input current 3mA or greater, sinking style input) Output 32 DC24V (output voltage DC24V, +/- 3V at 100mA) Additional 32/32 or 64/64 for a total of 64/64 or 96/96 I/O) Recorded point is played back with XYZ parallel shift amount Palletizing & de-palletizing teaching programmed by integrated user friendly pattern definition  JIS SLIM language Offline programming software tool (ICS Triplx ISaGRAF Workbench)  A selection from 8 (0-1000mm) of in-position accuracy can be designated on each step. In-position or path-through can also be designated 32 unique tools can be defined for use on taught positions.  Automated tool length calculation by selecting taught program  Automated tool length calculation by selecting taught program  Automated tool weight and COG is calculated by running designated program  Automated tool omoment of inertia is calculated by running designated program  Automated tool omoment of inertia is calculated by running designated program  Automated tool omoment of inertia is calculated by running designated program  Automated tool points for use with Soft-PLC  1. Screen Editor – addition, deletion and copy of every move step and function is available; recorded position can also be edited  2. Copy Utility – recorded program and step can be copied
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